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# Towards the assimilation of objects based on radar reflectivities on the convective scale with KENDA

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- component are objects derived from 3D radar reflectivities

### **COSMO-KENDA**

In March 2017 the Kalman filter for convective-scale data assimilation, which has been developed for the Consortium for Small-scale Modelling (COSMO) model, has become

## Radar data assimilation

In combination with the Efficient Modular VOlume scanning RADar Operator EMVORADO (Zeng2016, Bick2016), the direct assimilation of 3D radar data (reflectivity, radial wind) is possible.

Fig. 2: Example of radar reflectivity objects as obtained from Nowcasting (Konrad 3D) including cell-tracks.

Direct assimilation of individual objects compared to pure radar reflectivities may lead to

- Reduction of the amount of data
- Avoidance of the double penalty



Fig. 1: Sketch of the idea of texture assimilation.

#### **Assimilation of texture/features**

In this approach we aim to assimilate 2D textural information obtained from a certain horizontal scale. In Fig. 1 a sketch of the idea is shown

- Black squares indicate that corresponding pixel fulfills a desired constraint (e.g. exceedance of an adaptive threshold in a reflectivity composite, part of an object of size X)
- At the red square the average number of black squares in the green box is used as a texture observation. The term texture can be understood by considering that the distribution of the derived texture observations (e.g. red

# operational at DWD (Schraff2016, Fig. 3)



Fig. 3: COSMO-KENDA system.

The Kilometre-scale ENsemble Data Assimilation system *KENDA* renders the assimilation of any type of observation, given a corresponding forward operator, possible. Therefore KENDA allows to assimilate data based on objects and texture in a natural way.



- Vast amount of data
- Representativity error
- Observation error correlation
- Impact of the double penalty problem.

## Radar objects

A different view on radar reflectivities is given by the concept of objects which might be defined as

- Areas of connected grid points fulfilling certain conditions (e.g. thresholding and connection criteria to describe cores of convective cells)
- Numbers parametrizing gridded areas geometrically, as e.g. given by the Nowcasting-Tool Konrad3D (M.Werner, DWD), see Fig. 2).



problem.

#### However, this requires to

- Find a proper matching algorithm
- Develop techniques to facilitate the application of a LETKF ("fail objects", harmonization of the ensemble). Nonetheless it would be desirable to assimilate attributes of objects to
- Connect NWP and Nowcasting
- Potentially improve the skill of the system with regard to convection
- Access scale-dependent information encoded in radar objects.



Fig.4: FSS (25 grid points) for precipitation of ensemble with and without texture (T=30dbZ, scale=7) assimilation

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square in Fig. 1) is freely selectable. Therefore, by using overlapping regions, the texture may be scanned and assimilated. It is important to note that in this approach

- The localization radius and the scale are to be linked
- The vertical localization and localization radius have to be carefully tested
- Double counting of data may happen
- Some information might not be used (e.g. data below threshold).



3D radar data -

deterministic forecasts [4 days, 17 UTC runs].

Fig.5: FSS (21 grid points) of deterministic forecasts for

reflectivity>30 dbZ [4 days, hourly between 10-18 UTC].

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