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Assimilation of Temperature and Humidity Profiles from a Raman Lidar

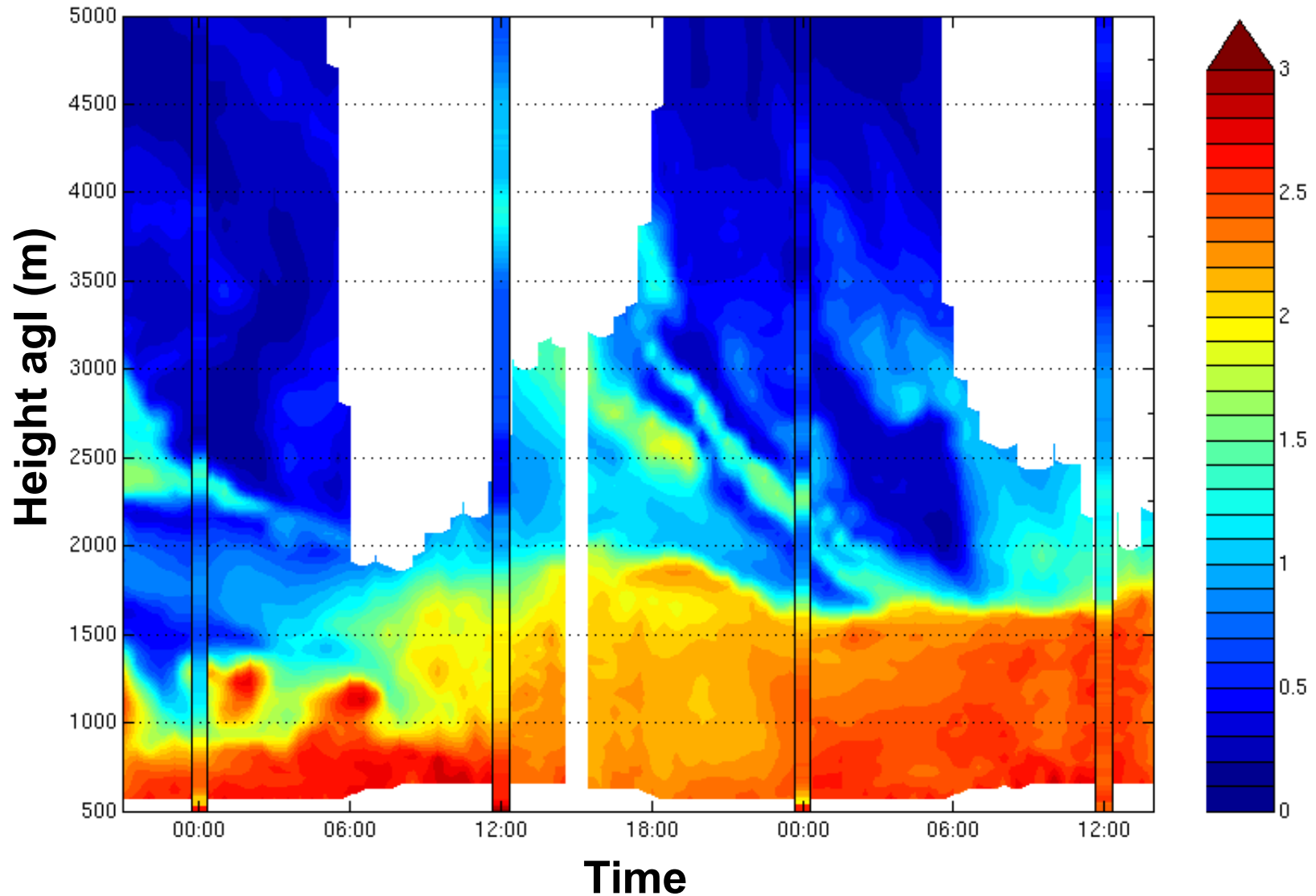
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MeteoSwiss, Switzerland

thanks to Christoph Schraff (DWD) for support

6th International Symposium on Data Assimilation, 5.-9. March 2018
LMU Munich



Raman Lidar Humidity Profiles





Introduction

- Lack of temperature and humidity obs in PBL
- Raman Lidar can provide temperature and humidity profiles with high temporal and vertical resolution
- Investigate impact of Lidar profiles in the operational, convective-scale ensemble DA and NWP system of MeteoSwiss
- Two case studies: a convection and a low stratus case



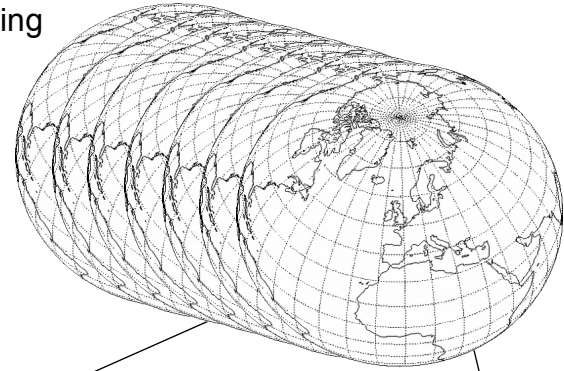
The MeteoSwiss NWP and DA System

The NWP System

- COSMO Model
- 2.2km grid spacing
- explicit deep convection
- 21 member
- 2 forecasts per day to +120h

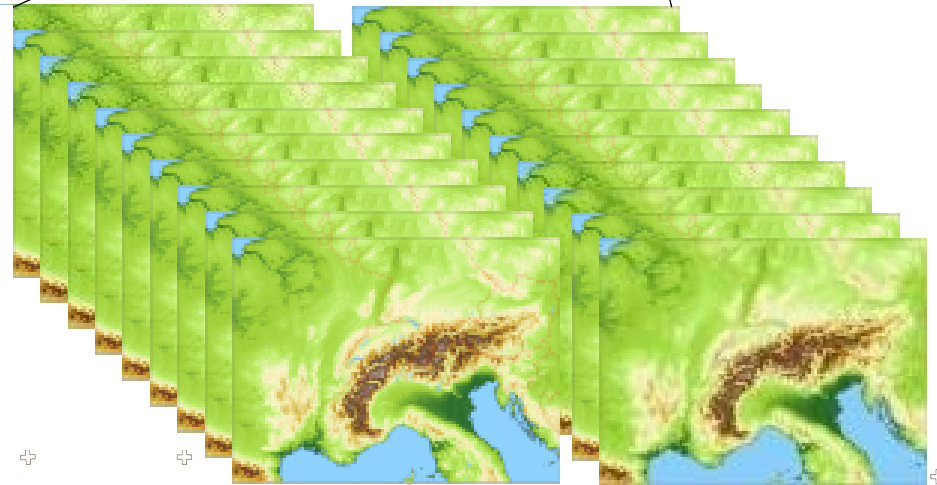
ECMWF-Model

18 km gridspacing
4 x per day



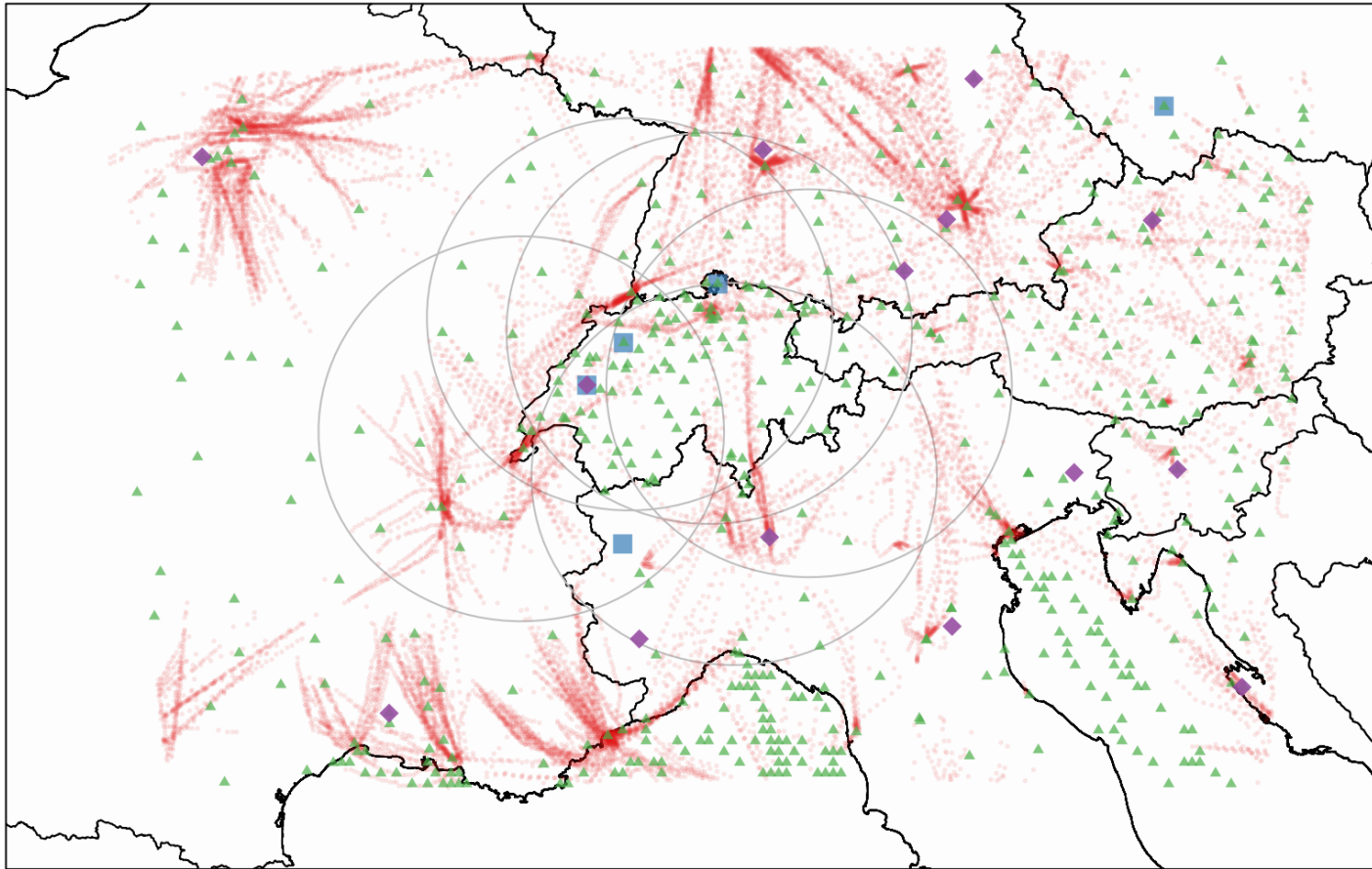
The DA System

- COSMO KENDA (Schraff et al., 2016)
- Based on LETKF (Hunt et al., 2004)
- 40 member
- Multiplicative and additive covariance inflation, RTPP





Assimilated Observations



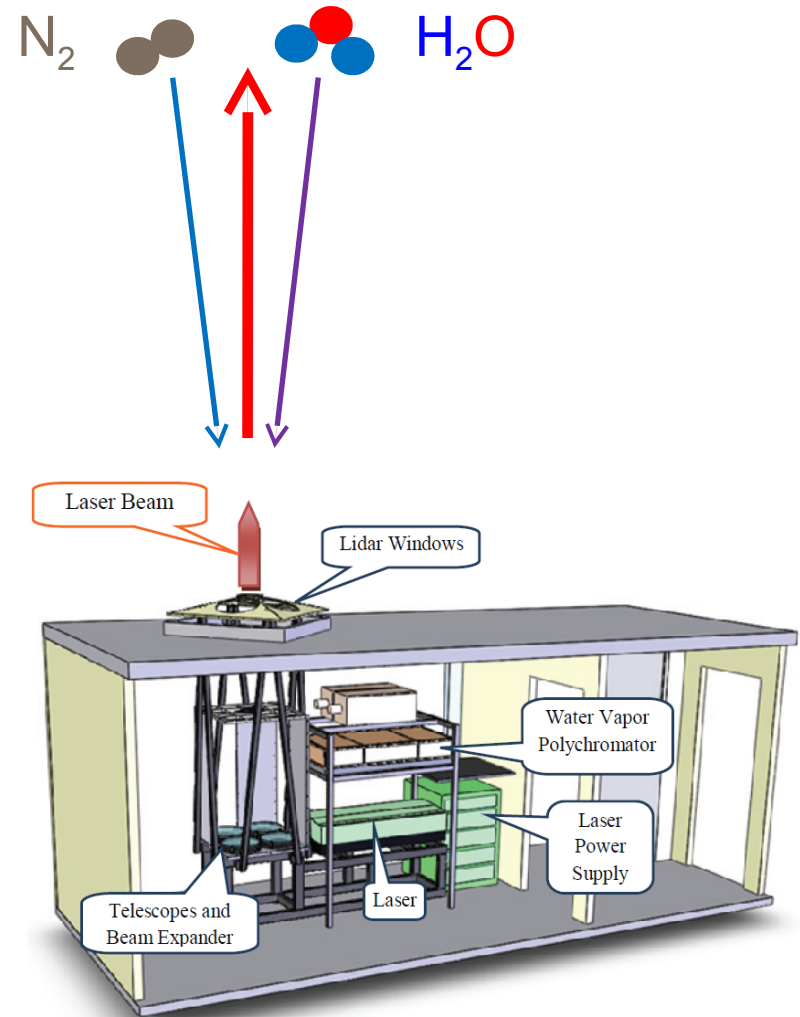
- ◆ Radiosondes
- ▲ Surface and Ships
- Windprofiler
- Aircraft
- Radar (LHN)



Raman Lidar for Opr Meteorology: RALMO

Observation specifications

- Water vapor mass mixing ratio
- Temperature
- Time resolution: 30 min
- Vertical range (day / night):
60 – 5000 m / 10'000 m
- Vertical height bins of 30-300m
- Error: 10% WV MMR / 0.5 K
- 7/24 automatic operation

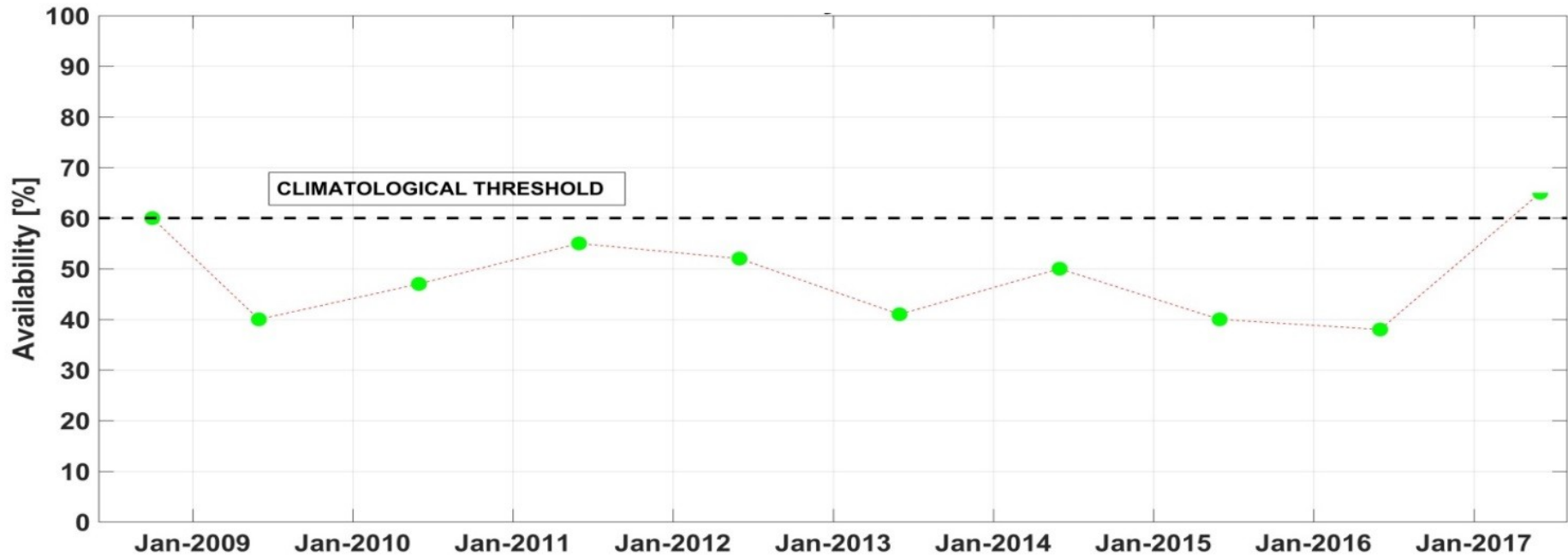




Availability of the Payerne Lidar Obs

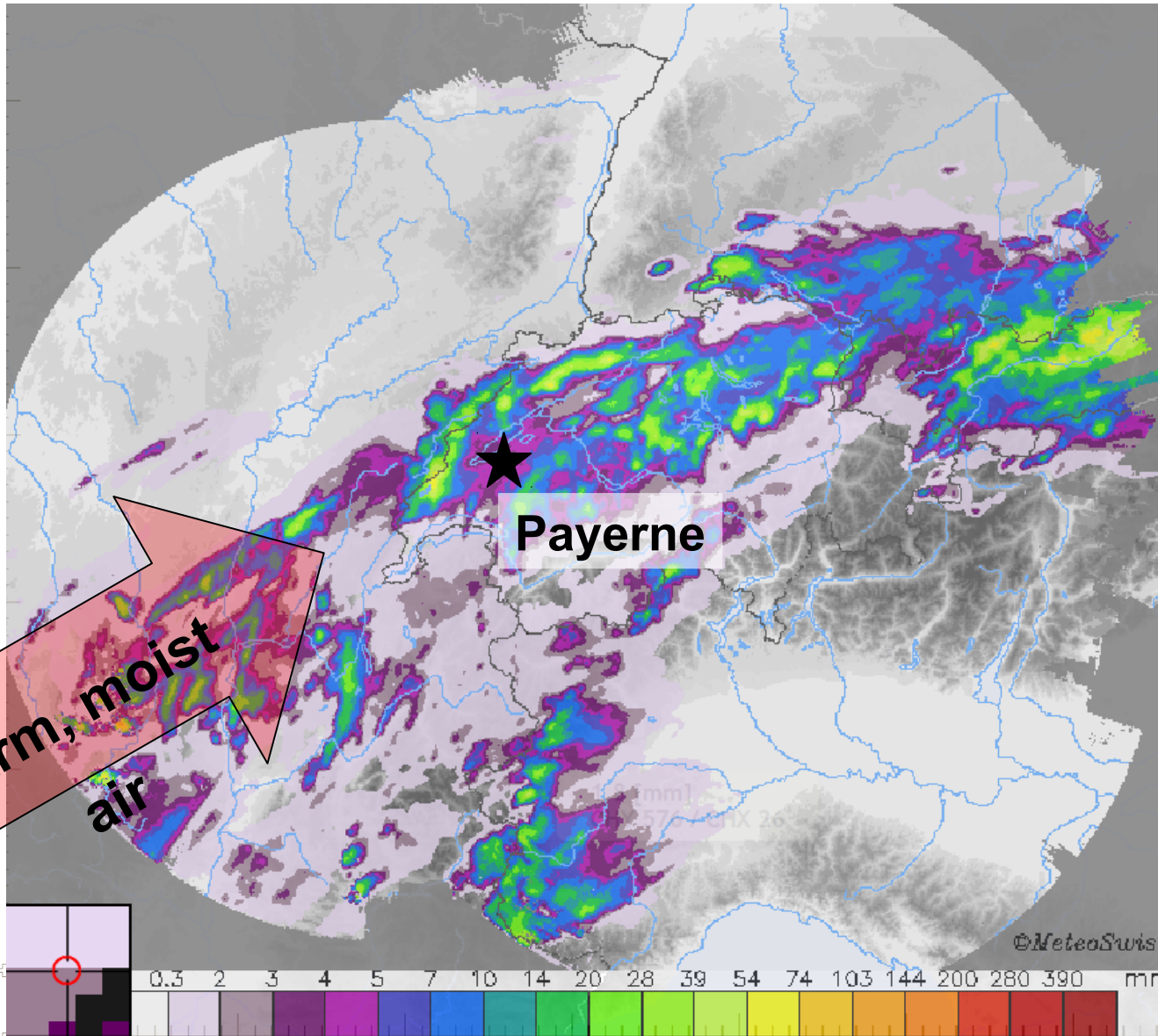
Does not work in rain and low clouds

Climatological availability: 60%



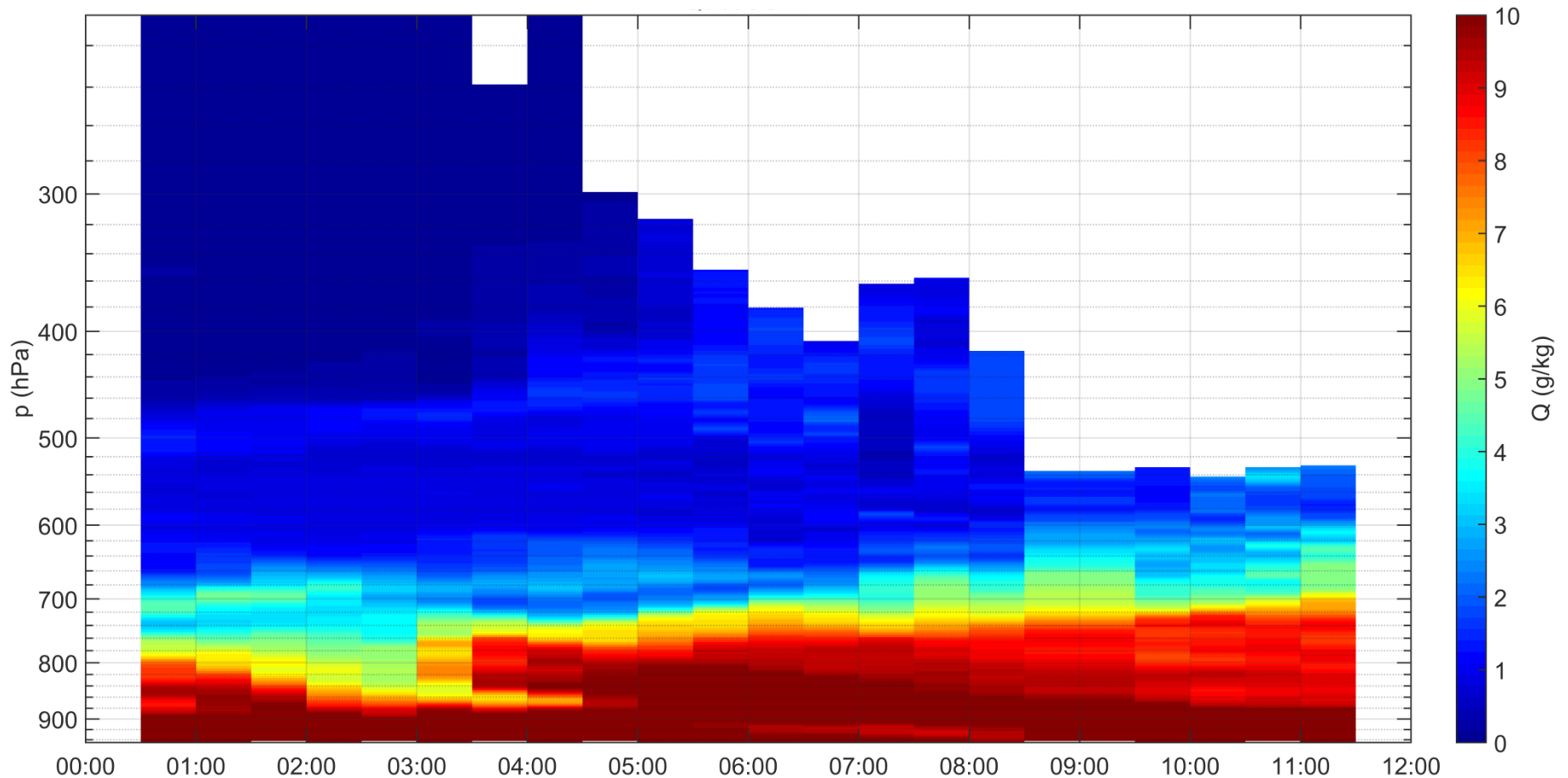


Case study of 24.08.2017





Mixing Ratio observed by Lidar





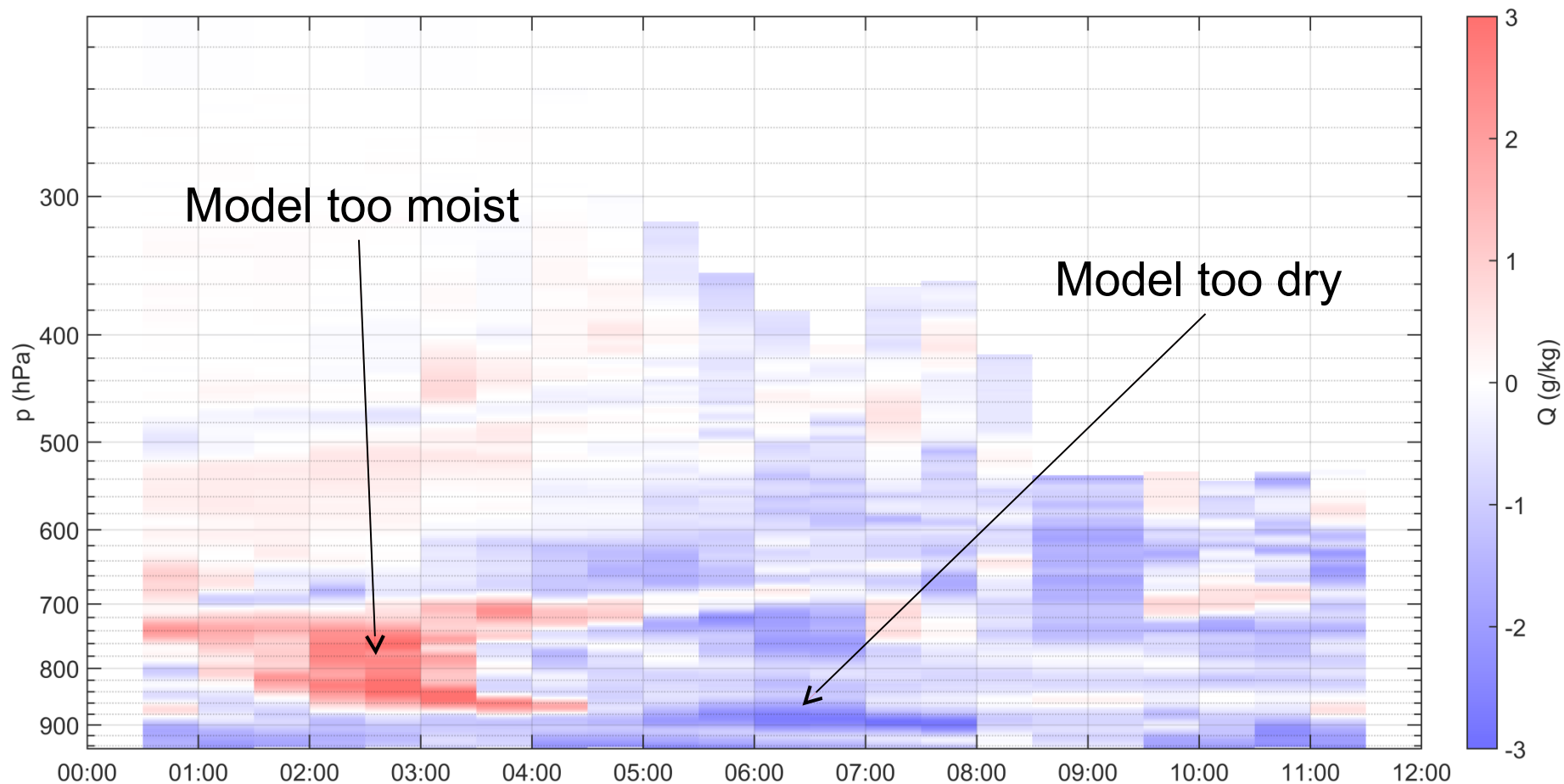
Experimental Setup

- KENDA assimilation from 00UTC to 12UTC
 - CONV (assimilation of conventional and Radar obs)
 - LIDAR (additional assimilation of Lidar T and RH profiles)
- COSMO-E forecasts (CTRL and ensemble) started at 12UTC from CONV and LIDAR analyses
- CTRL forecast initialized by KENDA ensemble mean



CONV Analysis Mean vs Lidar Obs

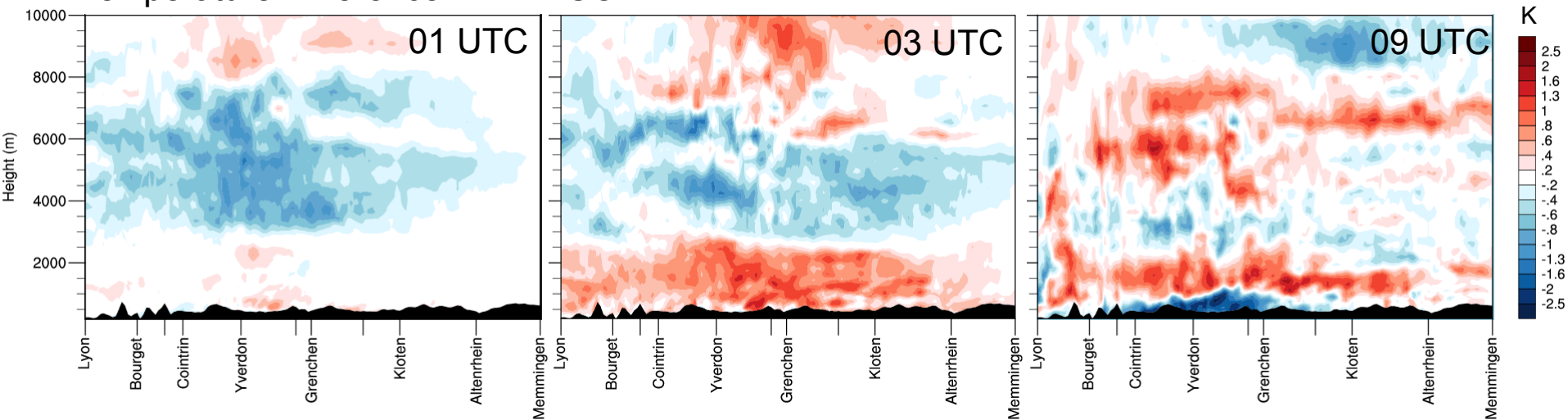
Water vapour mixing ratio difference



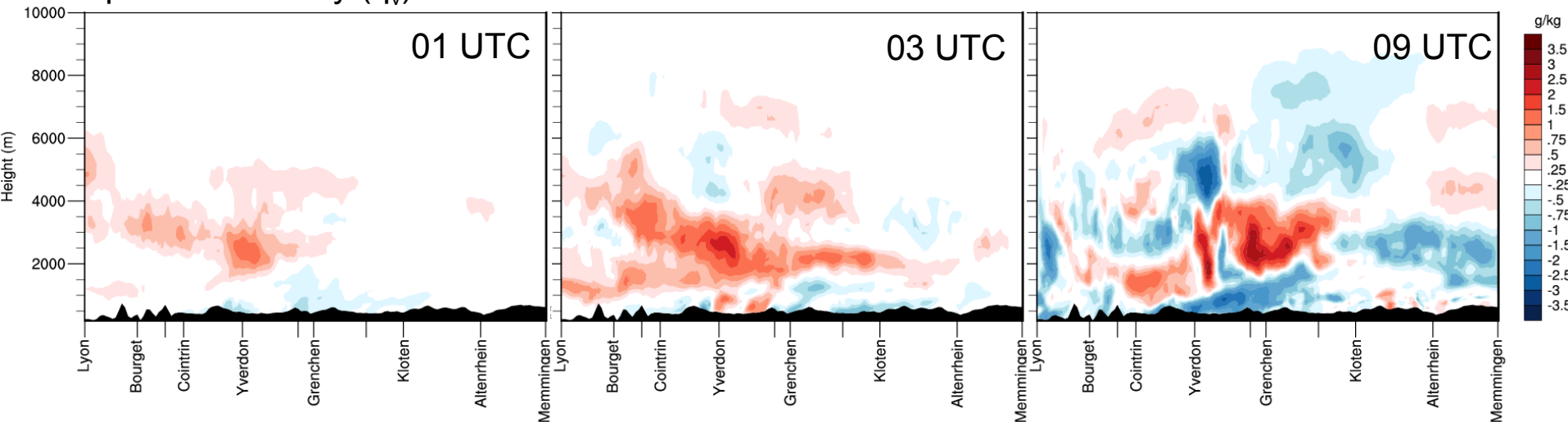


Effect of Lidar Obs on Analysis Means

Temperature Difference LIDAR-CONV



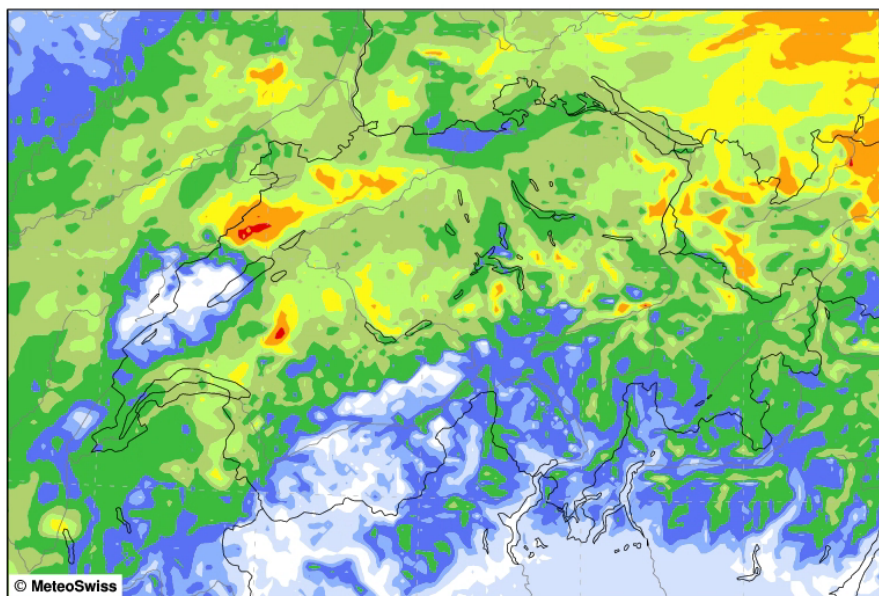
Specific Humidity (q_v) Difference CONV-LIDAR



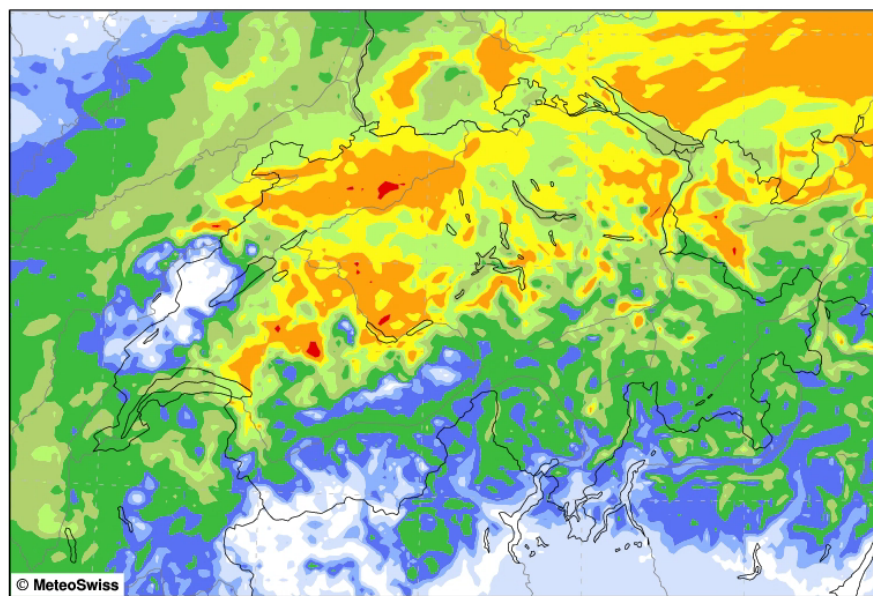


Pre-convective Environment

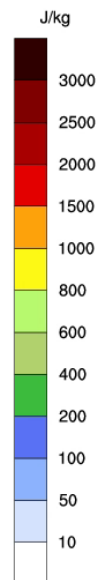
CAPE of Analysis Means valid at 12UTC (IC of forecasts)



CONV



LIDAR

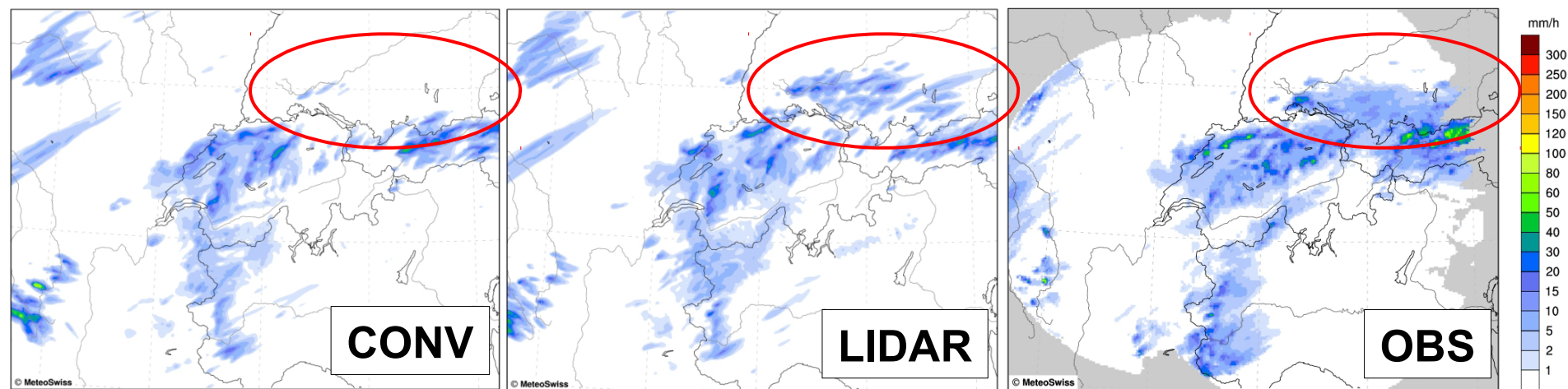




Precipitation Forecasts

Deterministic CTRL Forecasts initialized at 12UTC

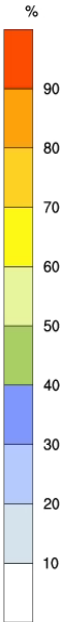
24h Precipitation sums ending at 25.08.2018 12UTC





CONV

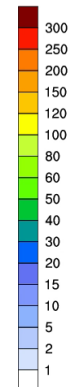
LIDAR



MeteoSwiss

OBS

mm/h



je

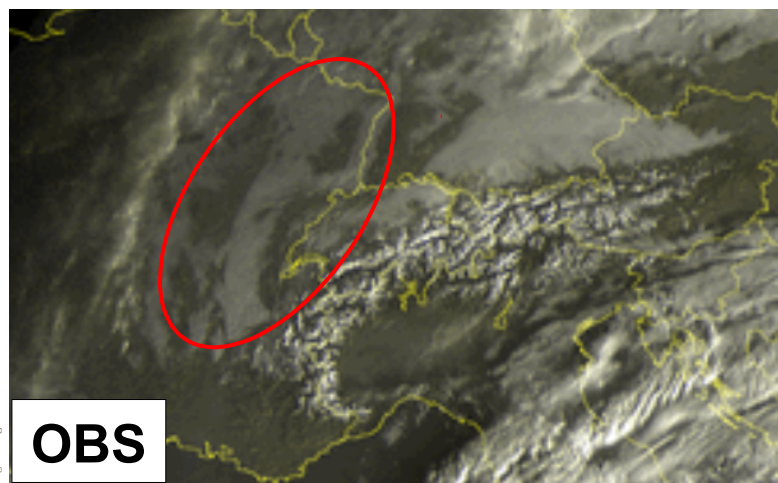
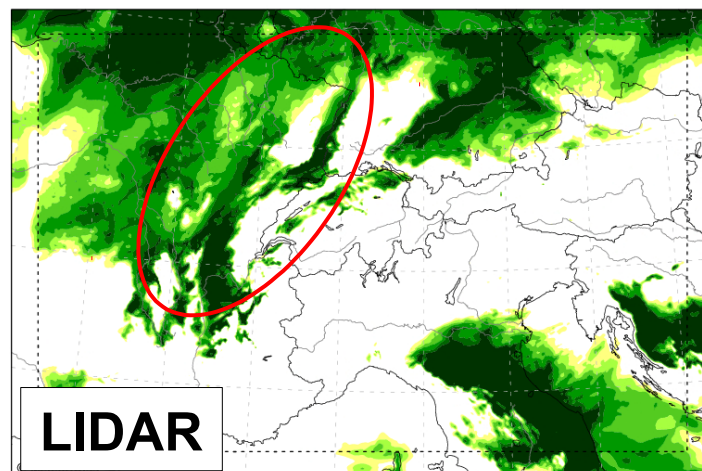
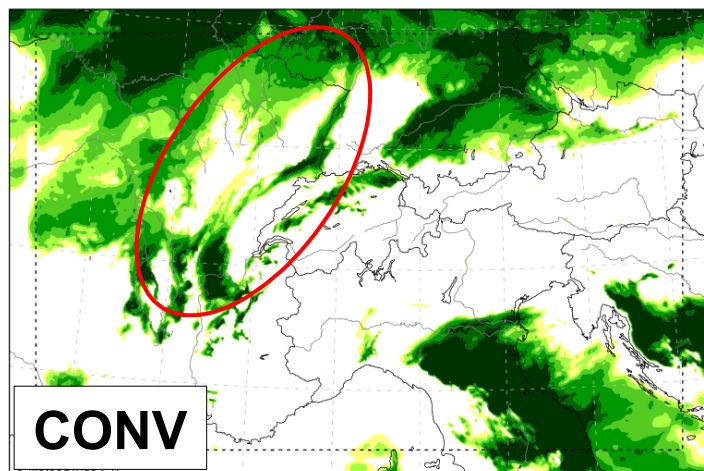
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Effect of Lidar Obs on Low Clouds

Analysis means of low clouds versus SEVIRI VIS

15.11.2017, 07UTC



MeteoSwiss



Summary

- Raman Lidar observations close a gap in PBL observation system
- Continuous temperature and humidity profiles from Lidar in Payerne (avg availability of 60%)
- Quality approaching that of radiosonde observations
- Successful assimilation with COSMO KENDA for a convection and low stratus case
- Lidar obs successfully adjusted the pre-convective environment, allowing for a more skillful precipitation forecast
- Impact smaller for the low stratus case



Outlook

- Extend assimilation experiments to longer periods
- Introduce new observation type in COSMO KENDA
- Adjust horizontal localization (smaller radius?)
- Adjust observation error